


11.2 Specifications of Servo Motor (ECMA Series)

Low Inertia Servo Motor

Model: ECMA Series	C204	C206		C208		C209		C210	
	01	02	04	04	07	07	10	10	20
Rated output power (kW)	0.1	0.2	0.4	0.4	0.75	0.75	1.0	1.0	2.0
Rated torque (N-m) ^{*1}	0.32	0.64	1.27	1.27	2.39	2.38	3.18	3.18	6.37
Maximum torque (N-m)	0.96	1.92	3.82	3.82	7.16	7.14	8.78	9.54	19.11
Rated speed (r/min)	3000								
Maximum speed (r/min)	5000					3000		5000	
Rated current (A)	0.90	1.55	2.60	2.60	5.10	3.66	4.25	7.30	12.05
Maximum current (A)	2.70	4.65	7.80	7.74	15.3	11	12.37	21.9	36.15
Power rating (kW/s) (without brake)	27.7	22.4	57.6	22.1	48.4	29.6	38.6	38.1	90.6
Rotor moment of inertia ($\times 10^{-4}$ kg.m ²) (without brake)	0.037	0.177	0.277	0.68	1.13	1.93	2.62	2.65	4.45
Mechanical time constant (ms) (without brake)	0.75	0.80	0.53	0.73	0.62	1.72	1.20	0.74	0.61
Torque constant-KT (N-m/A)	0.36	0.41	0.49	0.49	0.47	0.65	0.75	0.43	0.53
Voltage constant-KE (mV/(r/min))	13.6	16.0	17.4	18.5	17.2	27.5	24.2	16.8	19.2
Armature resistance (Ohm)	9.30	2.79	1.55	0.93	0.42	1.34	0.897	0.20	0.13
Armature inductance (mH)	24.0	12.07	6.71	7.39	3.53	7.55	5.7	1.81	1.50
Electrical time constant (ms)	2.58	4.30	4.30	7.96	8.36	5.66	6.35	9.30	11.4
Insulation class	Class A (UL), Class B (CE)								
Insulation resistance	>100M Ω , DC 500V								
Insulation strength	1500V AC, 60 seconds								
Weight (kg) (without brake)	0.5	1.2	1.6	2.1	3.0	2.9	3.8	4.3	6.2
Weight (kg) (with brake)	0.8	1.5	2.0	2.9	3.8	3.69	5.5	4.7	7.2
Max. radial shaft load (N)	78.4	196	196	245	245	245	245	490	490
Max. thrust shaft load (N)	39.2	68	68	98	98	98	98	98	98
Power rating (kW/s) (with brake)	25.6	21.3	53.8	22.1	48.4	29.3	37.9	30.4	82.0
Rotor moment of inertia ($\times 10^{-4}$ kg.m ²) (with brake)	0.04	0.192	0.30	0.73	1.18	1.95	2.67	3.33	4.95
Mechanical time constant (ms) (with brake)	0.81	0.85	0.57	0.78	0.65	1.74	1.22	0.93	0.66
Brake holding torque [Nt-m (min)]	0.3	1.3	1.3	2.5	2.5	2.5	2.5	8.0	8.0
Brake power consumption (at 20°C) [W]	7.2	6.5	6.5	8.2	8.2	8.2	8.2	18.5	18.5

Model: ECMA Series	C204		C206		C208		C209		C210	
	01	02	04	04	07	07	10	10	20	
Brake release time [ms (Max)]	5	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	25	70	70	70	70	70	70	70	70	70
Vibration grade (um)	15									
Operating temperature	0 ~ 40°C									
Storage temperature	-10 ~ 80°C									
Operating humidity	20% to 90% RH (non-condensing)									
Storage humidity	20% to 90% RH (non-condensing)									
Vibration capacity	2.5G									
IP rating	IP65 (when waterproof connectors are used, or when an oil seal is used to be fitted to the rotating shaft (an oil seal model is used))									
Approvals										

Footnote:

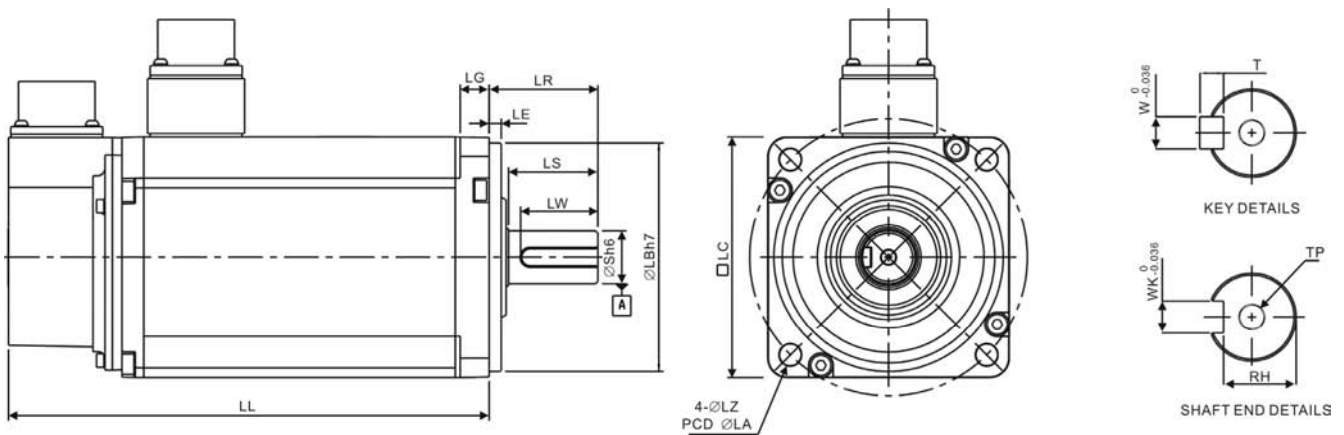
- *1 Rate torque values are continuous permissible values at 0~40°C ambient temperature when attaching with the sizes of heatsinks listed below:
 ECMA-__04 / 06 / 08 : 250mm x 250mm x 6mm
 ECMA-__10 : 300mm x 300mm x 12mm
 ECMA-__13 : 400mm x 400mm x 20mm
 ECMA-__18 : 550mm x 550mm x 30mm
 Material type : Aluminum – F40, F60, F80, F100, F130, F180
- *2 For the specifications of the motors with rotary magnetic encoders, please refer to the specifications of the corresponding standard models.

 **NOTE**

- 1) Please refer to Section 1.2 for details about the model explanation.

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Motor Frame Size: 100mm ~ 130mm Models



Model	G21303□S	E21305□S	G21306□S	G21309□S	C21010□S
LC	130	130	130	130	100
LZ	9	9	9	9	9
LA	145	145	145	145	115
S	$22^{+0}_{-0.013}$	$22^{+0}_{-0.013}$	$22^{+0}_{-0.013}$	$22^{+0}_{-0.013}$	$22^{+0}_{-0.013}$
LB	$110^{+0}_{-0.035}$	$110^{+0}_{-0.035}$	$110^{+0}_{-0.035}$	$110^{+0}_{-0.035}$	$95^{+0}_{-0.035}$
LL (without brake)	147.5	147.5	147.5	163.5	153.3
LL (with brake)	183.5	183.5	183.5	198	192.5
LS	47	47	47	47	37
LR	55	55	55	55	45
LE	6	6	6	6	5
LG	11.5	11.5	11.5	11.5	12
LW	36	36	36	36	32
RH	18	18	18	18	18
WK	8	8	8	8	8
W	8	8	8	8	8
T	7	7	7	7	7
TP	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20

NOTE

- 1) Dimensions are in millimeters.
- 2) Dimensions and weights of the servo motor may be revised without prior notice.
- 3) The boxes (□) in the model names are for optional configurations. (Please refer to section 1.2 for model explanation.)
- 4) For the specifications of the motors with rotary magnetic encoders, please refer to the specifications of the corresponding standard models.