# ATV12H018M2

variable speed drive ATV12 - 0.18kW - 0.25hp - 200..240V - 1ph



#### Main

Range of product	Altivar 12
Product or component type	Variable speed drive
Product destination	Asynchronous motors
Product specific application	Simple machine
Assembly style	On base plate
Component name	ATV12
Quantity per set	Set of 1
EMC filter	Integrated
Built-in fan	Without
Network number of phases	Single phase
[Us] rated supply voltage	200240 V (- 1510 %)
Motor power kW	0.18 kW
Motor power hp	0.25 hp
Communication port protocol	Modbus
Line current	2.8 A at 240 V 3.4 A at 200 V
Speed range	120
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor
Asynchronous motor control profile	Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/Frequency ratio (V/f)
IP degree of protection	IP20 without blanking plate on upper part
Noise level	0 dB

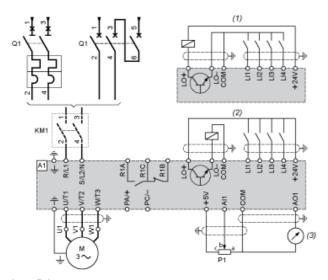
#### Complementary

Complementary	
Supply frequency	50/60 Hz (+/- 5 %)
Type of connector	1 RJ45 for Modbus on front face
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	38400 bit/s 19200 bit/s 9600 bit/s 4800 bit/s
Number of addresses	1247 for Modbus
Communication service	Read device identification (43) Read/Write multiple registers (23), messaging: 4/4 words maximum Write multiple registers (16), messaging: 27 words maximum Write single register (06), messaging: 29 words maximum Read holding registers (03), messaging: 29 words maximum
Prospective line Isc	<= 1 kA
Continuous output current	1.4 A at 4 kHz
Maximum transient current	2.1 A for 60 s
Speed drive output frequency	0.5400 Hz
Nominal switching frequency	4 kHz

Switching frequency	416 kHz with derating factor 216 kHz adjustable
Braking torque	Upto 70 % of nominal motor torque without braking resistor Upto 150 % of nominal motor torque with braking resistor at high inertia
Motor slip compensation	Adjustable Preset in factory
Electrical connection	L1, L2, L3, U, V, W, PA, PC terminal 3.5 mm² (AWG 12)
Tightening torque	0.8 N.m
Insulation	Electrical between power and control
Supply	Internal supply for logic inputs 24 V DC, voltage limits 20.428.8 V 100 mA for overload and short-circuit protection Internal supply for reference potentiometer 5 V DC, voltage limits 4.755.25 V 10 mA for overload and short-circuit protection
Analogue input number	1
Analogue input type	Al1 configurable voltage 05 V, impedance 30 kOhm Al1 configurable voltage 010 V, impedance 30 kOhm Al1 configurable current 020 mA, impedance 250 Ohm
Discrete input number	4
Discrete input type	(LI1LI4) programmable, 24 V, voltage limits 1830 V
Discrete input logic	Positive logic (source), 0< 5 V (state 0), > 11 V (state 1) Negative logic (sink), > 16 V (state 0), < 10 V (state 1), input impedance 3.5 kOhm
Sampling duration	< 20 ms, tolerance +/- 1 ms for logic input < 10 ms for analogue input
Linearity error	+/- 0.3 % of maximum value for analogue input
Analogue output number	1
Analogue output type	(AO1) software-configurable current, analogue output range 020 mA, output impedance 800 Ohm, analogue output resolution 8 bits (AO1) software-configurable voltage, analogue output range 010 V, output impedance 470 Ohm, analogue output resolution 8 bits
Discrete output number	2
Discrete output type	(R1A, R1B, R1C) protected relay output 1 C/O (LO+, LO-) logic output
Minimum switching current	5 mA at 24 V DC for logic relay
Maximum switching current	4 A at 30 V DC resistive load cos phi = 1 L/R = 0 ms for logic relay 3 A at 250 V AC resistive load cos phi = 1 L/R = 0 ms for logic relay 2 A at 30 V DC inductive load cos phi = 0.4 L/R = 7 ms for logic relay 2 A at 250 V AC inductive load cos phi = 0.4 L/R = 7 ms for logic relay
Acceleration and deceleration ramps	Linear from 0 to 999.9 s S U
Braking to standstill	By DC injection, 0.130 s
Protection type	Thermal motor protection via the drive by continuous calculation of l²t Against input phase loss in three-phase Short-circuit between motor phases Overheating protection Overcurrent between output phases and earth Line supply undervoltage Line supply overvoltage
Frequency resolution	Display unit 0.1 Hz Analog input converter A/D, 10 bits
Time constant	20 ms, tolerance +/- 1 ms for reference change
Marking	CE
Operating position	Vertical +/- 10 degree
Height	143 mm
Width	72 mm
Depth	102.2 mm
Product weight	0.7 kg

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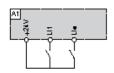
## Single-Phase Power Supply Wiring Diagram



- A1 Drive
- KM1 Contactor (only if a control circuit is needed)
- P1 2.2 k $\Omega$  reference potentiometer. This can be replaced by a 10 k $\Omega$  potentiometer (maximum).
- Q1 Circuit breaker
- (1) Negative logic (Sink)
- (2) Positive logic (Source) (factory set configuration)
- (3) 0...10 V or 0...20 mA

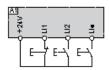
### **Recommended Schemes**

#### 2-Wire Control for Logic I/O with Internal Power Supply



LI1 : Forward LI• : Reverse A1 : Drive

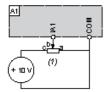
### 3-Wire Control for Logic I/O with Internal Power Supply



LI1: Stop LI2: Forward LI•: Reverse A1: Drive



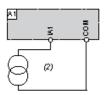
#### Analog Input Configured for Voltage with Internal Power Supply



(1) 2.2 k $\Omega$ ...10 k $\Omega$  reference potentiometer

A1: Drive

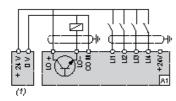
## Analog Input Configured for Current with Internal Power Supply



(2) 0-20 mA 4-20 mA supply

À1: Drive

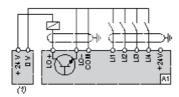
## Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply

A1: Drive

## Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply

À1: Drive

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